

★ **Week 2 reading: Tong chapter 1, and start chapter 2.**

<http://www.damtp.cam.ac.uk/user/tong/gaugetheory.html>

- Continue from last time with the  $\theta$  term.

$$S_{\theta,u(1)} = \int d^4x \frac{\theta}{4\pi^2\hbar c} \vec{E} \cdot \vec{B} = \int d^4x \frac{\theta}{32\pi^2\hbar c} \epsilon^{\mu\nu\rho\sigma} F_{\mu\nu} F_{\rho\sigma} = \hbar \int \theta c_1(F) \wedge c_1(F).$$

The normalization is such that  $S_\theta = \hbar\theta k$  with  $k \in \mathbf{Z}$  an integer (called the instanton number). Then  $e^{iS/\hbar}$  in the path integral is periodic in  $\theta \cong \theta + 2\pi$ . There are interesting variants, with different periodicities (e.g.  $4\pi$ ) on certain spacetime manifolds, and a discussion of such cases could make for a good final presentation topic.

- If  $\theta$  is replaced with a dynamical scalar field, the field is called the *axion*  $a$  (we had a recent colloquium by Frank Wilczek about this). The axion's field target space is a circle,  $a \cong a + 2\pi$ . Let's replace  $\theta \rightarrow \theta(t, \vec{x})$ , which could either be the dynamical axion or an external background source for the operator  $\tilde{F}^{\mu\nu} F_{\mu\nu}$ . The classical EOM for  $A_\mu$  become:

$$\begin{aligned} \nabla \cdot \vec{E} &= j_e^0 - \frac{\alpha c}{\pi} \nabla \theta \cdot \vec{B}, & \alpha &\equiv e^2/4\pi\hbar c, \\ -\frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} + \nabla \times \vec{B} &= \vec{j}_e + \frac{\alpha}{\pi c} (\dot{\theta} \vec{B} + \nabla \theta \times \vec{E}), \end{aligned}$$

where  $j_e^\mu$  is the electric current associated with matter fields. The fact that  $\theta$  enters the EOM only via derivative terms, so it drops out of the EOM if  $\theta$  is a constant, fits with the fact that  $\theta$  is the coefficient of a total derivative term. The fact that it is the total derivative of a gauge non-invariant does not affect the fact that it drops out of the EOM; this is a general aspect of topological terms. For example, there are intergalactic magnetic fields which, with a varying  $\theta$ , can source electric fields.

In absence of electric and magnetic sources, we set  $j_e^\mu = 0$ , and  $j_m^\mu = 0$ , and the other two Maxwell equations are unchanged,  $\nabla \cdot \vec{B} = 0$  and  $\partial_t \vec{B} + \nabla \times \vec{E} = 0$ . If we define  $\vec{D} = \epsilon_0(\vec{E} + \frac{\alpha c \theta}{\pi} \vec{B})$  and  $\vec{H} = \mu_0^{-1}(\vec{B} - \frac{\alpha \theta}{\pi c} \vec{E})$ , then  $\nabla \cdot \vec{D} = 0$  and  $\nabla \times \vec{H} - \partial_t \vec{D} = 0$ . At an interface where  $\theta$  changes, there are associated surface charges and currents. If there are no other external charges and currents, these follow from  $\hat{n} \cdot \Delta \vec{D} = 0$  and  $\hat{n} \times \Delta \vec{H} = 0$ . E.g. there are topological insulator materials which effectively have  $\theta = \pi$ . Consider an interface, e.g.  $\theta = \pi \Theta(-z)$ . Then if an external source makes  $\vec{B}$ , get surface electric charge density  $\sigma = \alpha c B \hat{n}$ . If an external source makes  $\vec{E}$ , get surface current density  $\vec{K} = \alpha \epsilon_0 c \vec{E} \times \hat{n}$ . This is a Hall conductivity  $\sigma = \frac{1}{2} \cdot \frac{e^2}{2\pi\hbar}$ .

- Dyons are objects with both electric charge  $q_e$  and magnetic charge  $q_m$ . The charge pair is written as  $(q_e, q_m)$ , so a basic electric charge is  $(1, 0)$  and a basic magnetic charge is  $(0, 1)$ . The generalization of Dirac's quantization argument is to consider an object of charges  $(q_{1,e}, q_{1,m})$  in the background of an object with charges  $(q_{2,e}, q_{2,m})$  and the resulting Dirac-Zwanziger quantization condition is  $q_{1,e}q_{2,m} - q_{2,e}q_{1,m} \in 2\pi\hbar Z$ .

- The Witten effect:  $\theta$  gives electric charge  $\sim \theta$  to magnetic monopoles. Suppose we take the minimum electric charge to be  $q_e = 1$ , and the minimum magnetic charge is then  $q_m = 2\pi\hbar$ . The minimum magnetic charge monopole becomes a dyon with electric charge  $q_e = \frac{\theta}{2\pi}$ . This can be understood from  $\partial_\mu\theta$  terms in the above EOM for  $\vec{E}$  and  $\vec{B}$ . If  $\theta$  is rotated from 0 to  $2\pi$ , the original monopole becomes a bound state of a monopole and an object of electric charge 1. There is a generalization for dyons, and it is compatible with the Dirac-Zwanziger quantization condition ( $\theta$  cancels).

- The gauge group of the Standard Model is  $su(3)_C \times su(2)_W \times u(1)_Y$  (there are some nice fine points about discrete symmetries that I might return to later, but ignore here). The  $u(1)_Y$  part is similar to the above, though with a crucial difference that the left and right-handed chiral Fermions have different  $q$  charges. The  $su(3)_C$  and  $su(2)_W$  gauge symmetries are somewhat similar, but there are several crucial differences. First, these symmetries are non-Abelian (recall the non-Abelian nature of  $su(2)$  as seen by rotating a book along two axes in different orders giving different final orientations). Also,  $su(2)_W$  is chiral: it only acts on left-handed Fermions; this is why the weak interactions violate  $P$ . Also,  $su(2)_W$  and  $u(1)_Y$  are broken to a  $u(1)_{EM}$  subgroup by the vacuum expectation value of a Bose condensate (the Higgs field), which is why the  $W_\mu^\pm$  and  $Z^\mu$  gauge fields are massive. I intend to discuss these and related topics further in this class.

- Let's start by discussing the analogs of  $D_\mu$  and  $F_{\mu\nu}$  in a gauge theory with non-Abelian group  $G$ . To be concrete, I will sometimes take  $G = SU(2)$ , but most of the discussion for now will be general. I will also sometimes use the notation of writing the gauge group, in lower case letters, e.g.  $su(2)$ , to distinguish a local gauge symmetry vs global symmetry. We can consider a pure Yang-Mills theory, which means only gauge fields and no matter representations, or we can include matter fields. The matter fields could be scalars (e.g. the Higgs in the SM)  $\phi$  or Fermions  $\psi$  (as in QED, these are Dirac if  $m \neq 0$  or, for  $m = 0$ , we can have left and / or right-handed chiral fermions – more on this shortly). The matter fields are in representations of the gauge group, and the most-discussed cases are the fundamental, anti-fundamental, and adjoint representations;

for  $su(2)$  the fundamental and anti-fundamental are  $\mathbf{2} \cong \bar{\mathbf{2}}$  (like  $j = \frac{1}{2}$  for the rotation group), and the  $\mathbf{3}$  adjoint representation (like  $j = 1$  for rotations).

Consider e.g.  $su(N)$  with  $\psi_\alpha^c$  in the fundamental, where  $\alpha = 1, 2$  is a spinor index and  $c = 1, \dots, N$  is the  $su(N)$  color index; the Lorentz index  $\alpha$  goes for the ride and will usually be suppressed. The  $su(N)$  gauge symmetry takes  $\psi^c \rightarrow U^c_d(x)\psi^d$  where we sum the repeated color index. Here  $U(x)$  is an element of the  $SU(N)$  group manifold (e.g. for  $SU(2)$  it's  $\cong S^3$ ):  $U^\dagger U = \mathbf{1}$  and  $\det U = 1$ , and we can thus write it as the exponential of Hermitian, traceless  $N \times N$  matrices; there are  $N^2 - 1$  of these and for the rotation group these are the 3 generators  $J^a$ . An anti-fundamental can be written as  $\tilde{\psi}_c$  which transforms as  $\tilde{\psi}_c \rightarrow U^{*d}_c \tilde{\psi}_d$  and  $U^\dagger U$  means that  $\delta_d^c$  is invariant and  $\det U = 1$  means that  $\epsilon_{c_1 \dots c_N}$  and  $\epsilon^{c_1 \dots c_N}$  are invariant. For  $SU(2)$ , the fundamental and anti-fundamental are related by  $\tilde{\psi}_c = \epsilon_{cd}\psi^d$ .

- We now want to write a covariant derivative, such that  $\psi \rightarrow U\psi$  takes  $D_\mu\psi \rightarrow D_\mu^U U\psi = UD_\mu\psi$ , so  $D_\mu^U = UD_\mu U^{-1}$ . Let's write it as  $D_\mu = \partial_\mu - iA_\mu$  (this changes the sign of  $A_\mu$  vs my convention for  $u(1)$ , to agree with the notation for the non-Abelian case in other references), with  $A_\mu = A_\mu^a T^a$ . Note that, when we write  $D_\mu = \partial_\mu - iA_\mu$ , it should be understood that  $A_\mu = A_\mu^a T_R^a$ , with  $R$  the representation of the field that it acts on. For example, if acting on something that is invariant, i.e. the trivial rep, then  $T_R^a = 0$  and  $D_\mu \rightarrow \partial_\mu$  (similar to how in GR the  $\nabla_\mu$  notation has implicit the connection, which depend on what it acts on, with e.g.  $\nabla_\mu \rightarrow \partial_\mu$  if acting on a scalar). For  $u(1)$ , the generator  $T_R^a \rightarrow q$ , the electric charge of the operator on which it acts. For  $su(2)$ , if acting on the rep labeled by  $I$  (analogous to  $j$  for the rotation group), then e.g.  $D_\mu = \partial_\mu \mathbf{1}_{2I+1} + iA_\mu^a T_{2I+1}^a$ , where from now on I will not explicitly write the  $\mathbf{1}$  or the  $R$  reminder that  $D_\mu$  depends on the representation of the field on which it acts.

We want  $D_\mu^U(U\psi) = UD_\mu\psi$ , i.e.  $\partial_\mu U - iA_\mu^U U = -iUA_\mu$ . So  $A_\mu^U = iU\partial_\mu U^{-1} + UA_\mu U^{-1}$ . As a check, for  $U(1)$  with  $U = e^{i\alpha}$  this gives  $A_\mu^U = \partial_\mu \alpha + A_\mu$ . More generally, taking  $U = \exp(i\alpha)$ , with  $\alpha = \alpha^a T^a$  and expand for an infinitesimal  $\alpha^a$ , get  $\delta A_\mu = D_\mu \alpha = \partial_\mu \alpha + [iA_\mu, \alpha]$ . Writing  $D_\mu^a = \partial_\mu - iA_\mu^a$ ,  $(D_\mu \alpha)^a = \partial_\mu \alpha^a - A_\mu^b \alpha^c f^{abc}$ .

The gauge field strength tensor corresponds to a commutator of covariant derivatives (analogous to the Riemann curvature tensor):

$$F_{\mu\nu} = i[D_\mu, D_\nu] = \partial_\mu A_\nu - \partial_\nu A_\mu - i[A_\mu, A_\nu] = F_{\mu\nu} = F_{\mu\nu}^a T^a,$$

$$F_{\mu\nu}^a = \partial_\mu A_\nu^a - \partial_\nu A_\mu^a + f^{abc} A_\mu^b A_\nu^c.$$

$F_{\mu\nu}$  is in the adjoint rep, transforming as  $F_{\mu\nu} \rightarrow F_{\mu\nu}^U = UF_{\mu\nu}U^{-1}$ . For  $U = \exp(i\alpha^a T^a)$  and  $\alpha^a$  infinitesimal, get  $\delta F_{\mu\nu} = i[\alpha, F_{\mu\nu}]$ , which is the statement that  $F_{\mu\nu}$  transforms in the adjoint rep. The Lagrangian density must of course be gauge invariant, and the gauge kinetic terms come from the quadratic casimir (squaring and taking the trace):  $\mathcal{L} \supset -\frac{1}{2g^2} \text{Tr}(F_{\mu\nu} F^{\mu\nu})$ . E.g. for  $G = SU(2)$ , we can use a notation inspired by the rotation group, where the  $j = 1$  adjoint is denoted by a 3d vector, so  $\vec{F} = \partial_\mu \vec{A}_\nu - \partial_\nu \vec{A}_\mu + \vec{A}_\mu \times \vec{A}_\nu$ , and the gauge kinetic terms are  $-\frac{1}{4g^2} \vec{F}_{\mu\nu} \cdot \vec{F}^{\mu\nu}$ .